



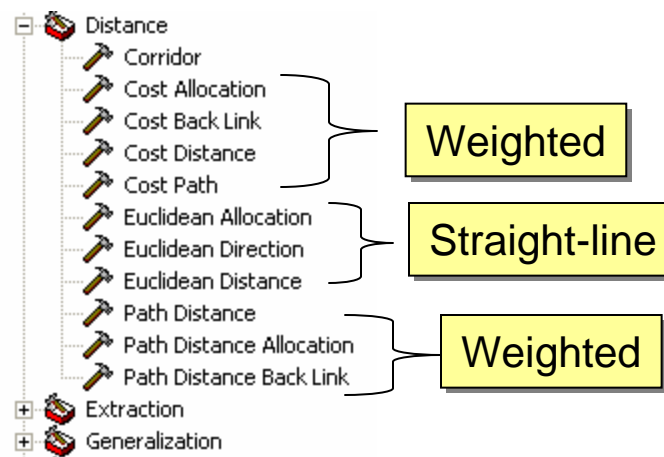
Distance Tools



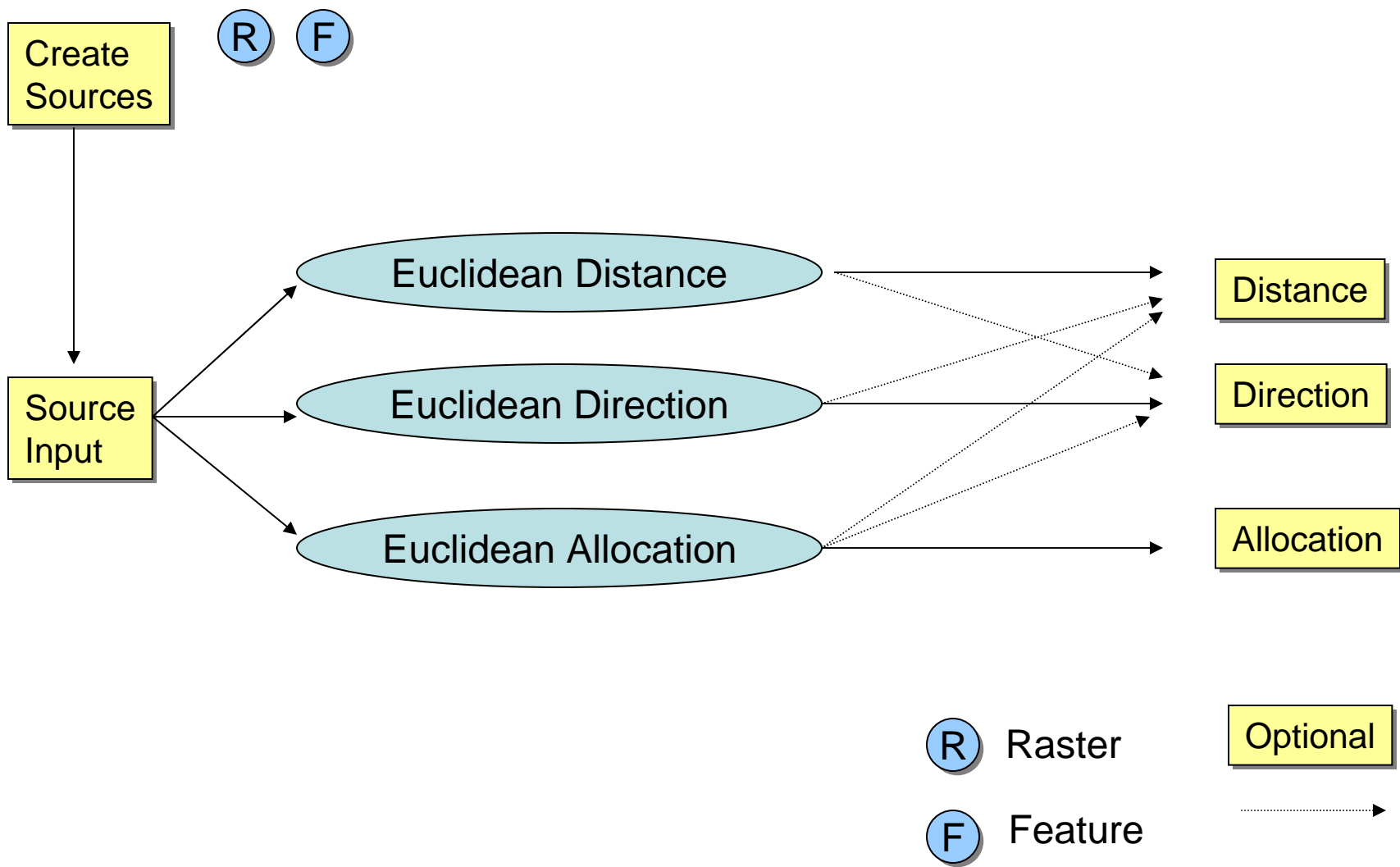
Lesson 6 overview

- ❑ **Straight-line distance**
- ❑ **Euclidean distance: Distance to closest store**
- ❑ **Euclidean allocation: ID of closest store**
- ❑ **Euclidean direction: Compass heading to closest store**
- ❑ **Weighted distance**
- ❑ **Inputs: Cost surface and sources**
- ❑ **Cost distance: How long to drive to closest store?**
- ❑ **Cost path: Best path to the closest store**
- ❑ **Corridor: Probability of travel between stores**
- ❑ **Exercise**

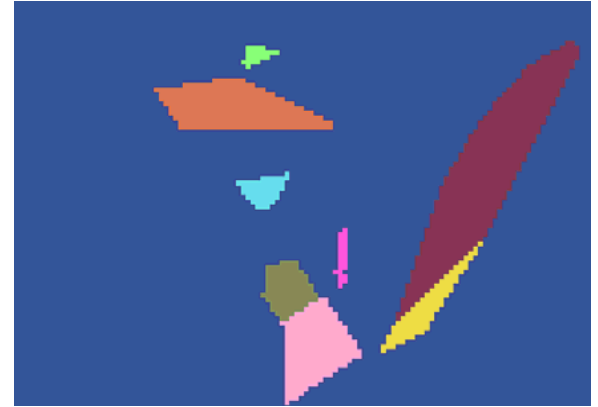
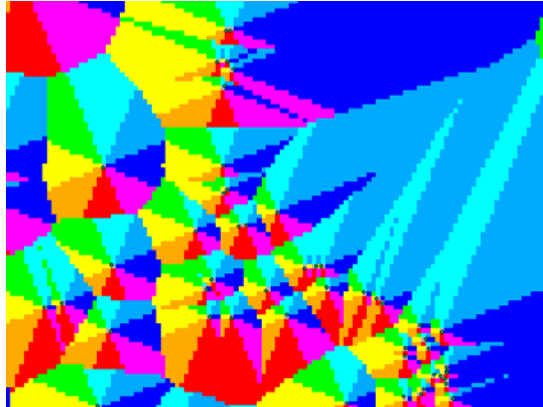
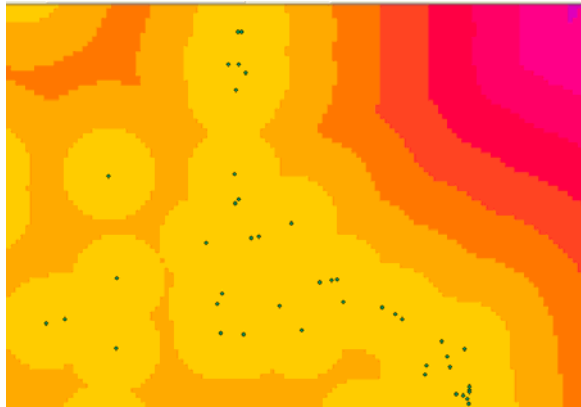
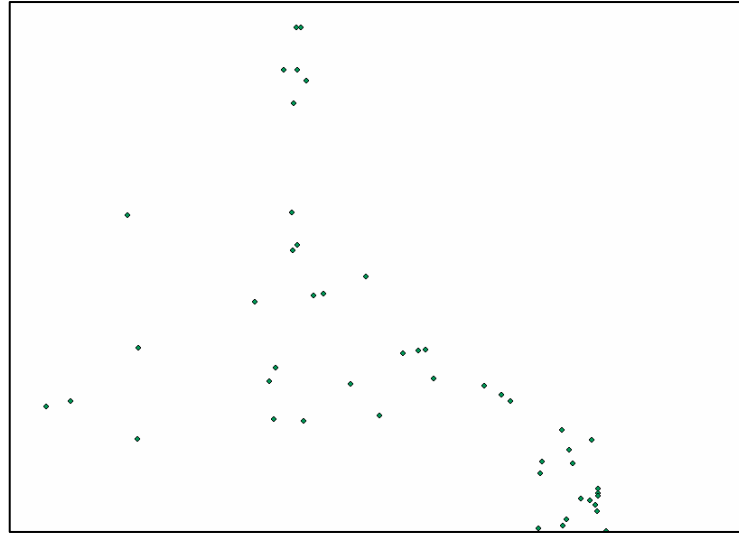
Distance tools



The roadmap - Euclidean distance

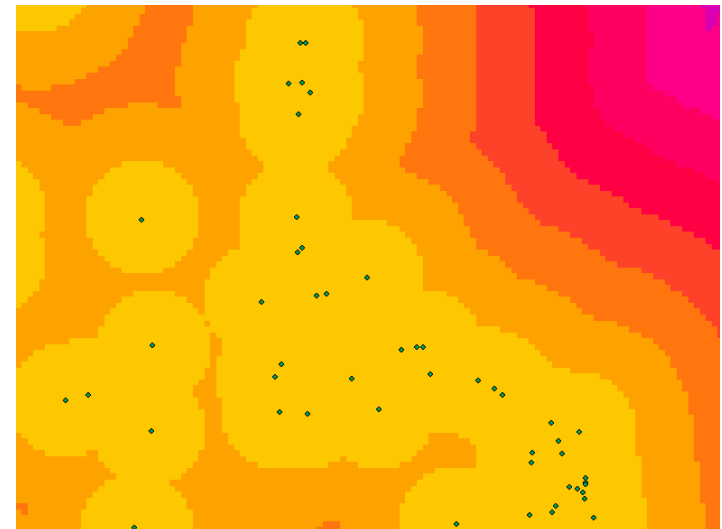
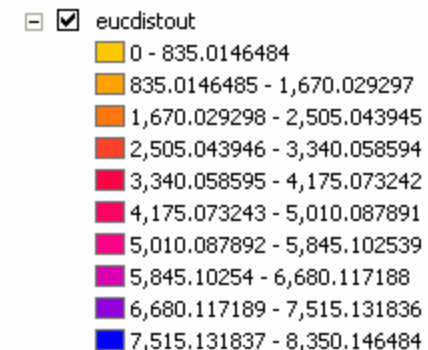


Euclidean tools output



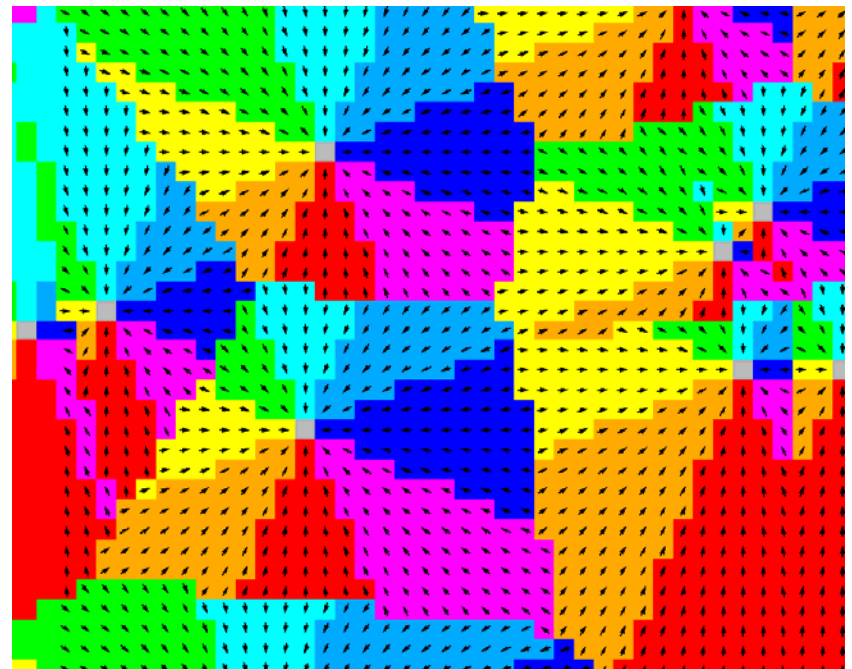
Calculating Euclidean distance

- ❑ Calculates straight-line distance
- ❑ From each cell to nearest source
- ❑ Cell center to cell center
- ❑ Output in map units (e.g., feet)
- ❑ Source cells are output as zero
- ❑ Must create sources first



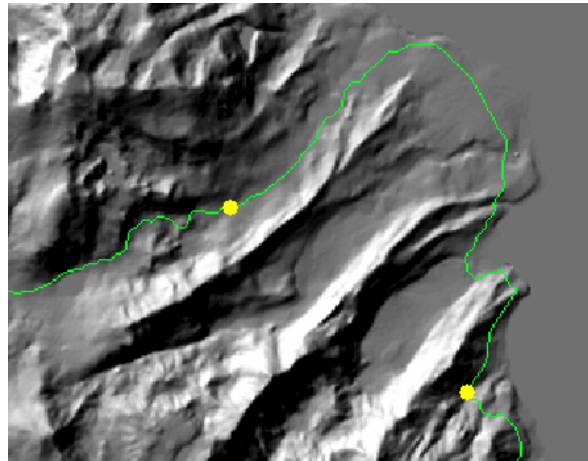
Euclidean direction and allocation

- ❑ **Direction output**
- ❑ **Compass heading from cell to nearest source, 0 to 360**
- ❑ **Allocation output**
- ❑ **Identity of the closest source cell**

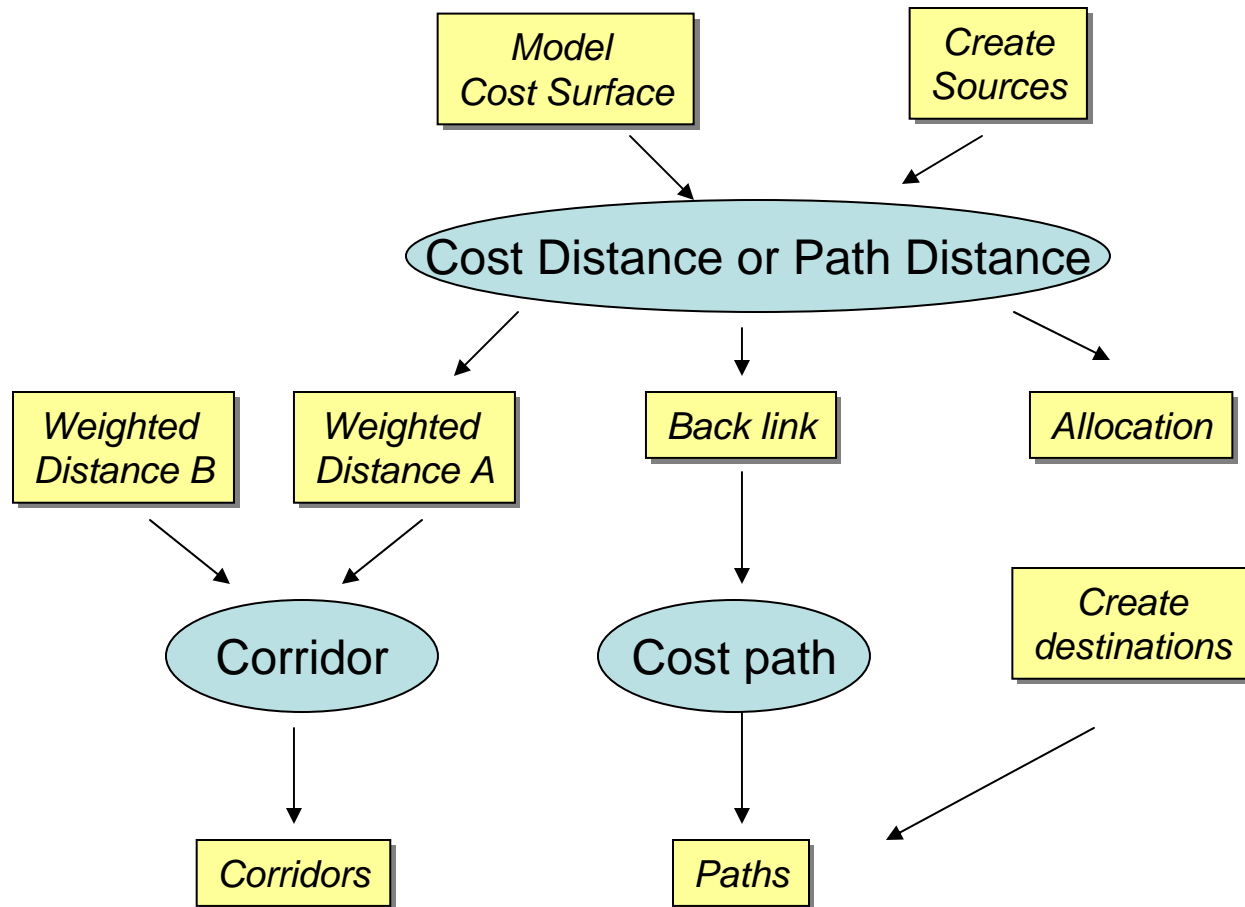


Weighted distance measurement

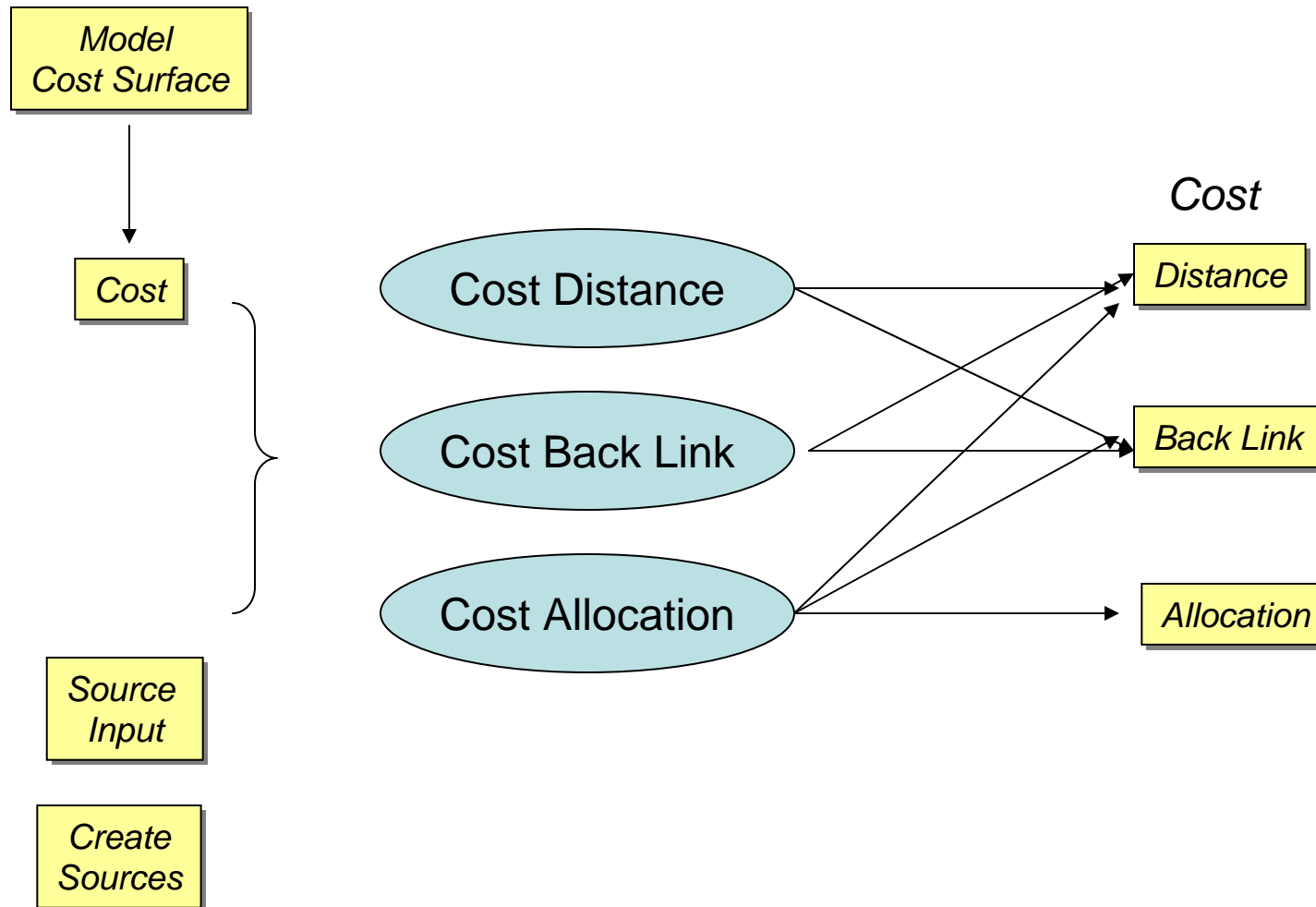
- ❑ The shortest path between points is not always the best:
- ❑ Ten hours to climb over the mountain
- ❑ Five hours to follow the trail around it
- ❑ Finds the least-cost path between cells and sources
- ❑ Considers resistance to travel; an input cost surface
- ❑ Weights distance with travel costs
- ❑ Result: Accumulated travel cost to every cell
- ❑ Units are cost (e.g., time, money), not distance



The roadmap - Weighted distance process

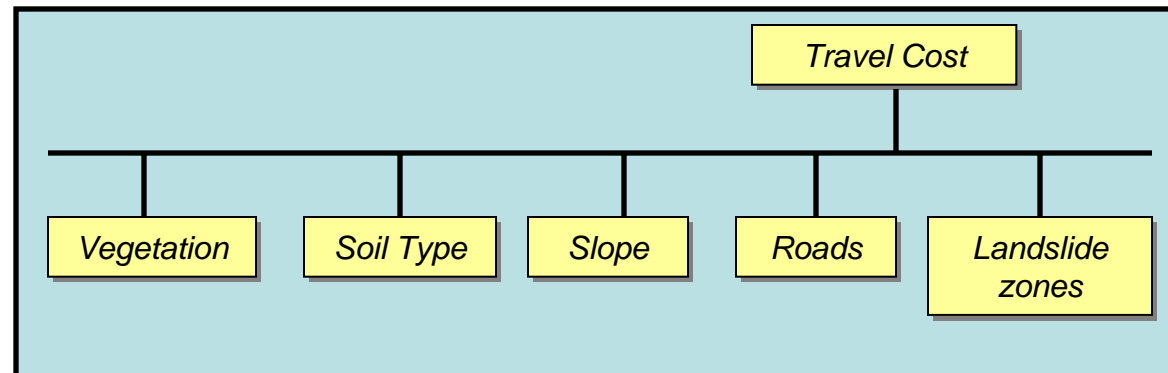
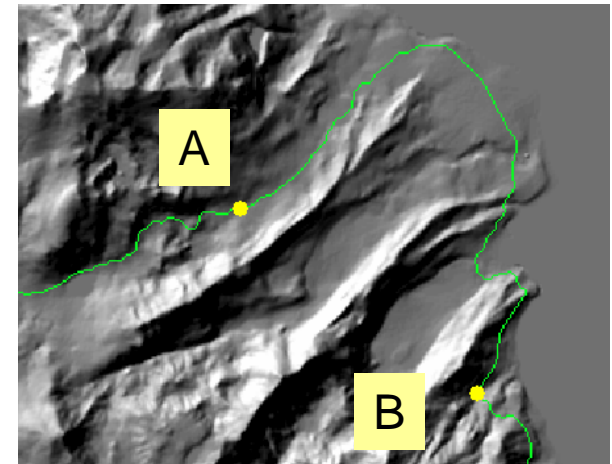


The roadmap - The Cost Distance tools



Creating the cost surface

- ❑ **Cost to travel through each cell**
 - High values = high travel cost
- ❑ **Express as cost per unit distance**
 - Dollars per foot, hours per meter, etc.
- ❑ **Usually created by modeling**
 - Often considers many variables



Calculating weighting distance

- ❑ Uses distance between cells and cost to cross the cells
- ❑ Find average cost for two cells, multiply by distance
 - Orthogonal distance = $(1 * \text{cell size})$
 - Diagonal distance = $(\sqrt{2} * \text{cell size})$

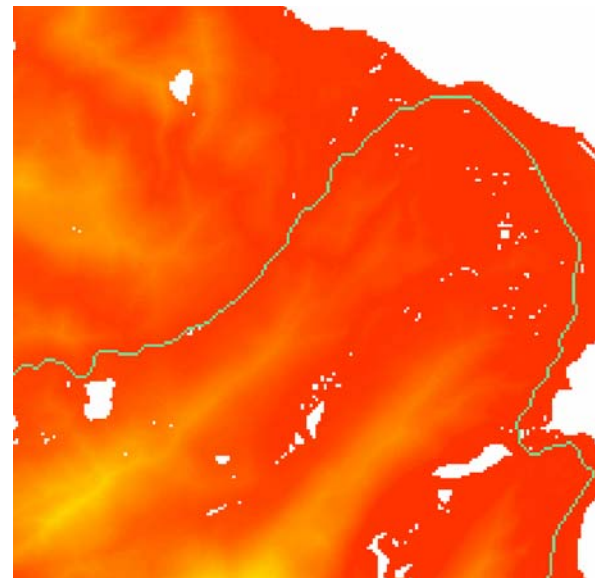
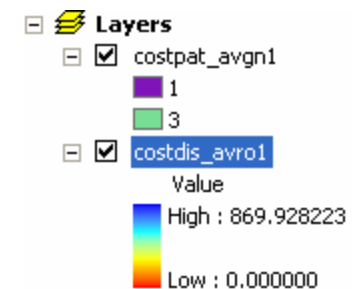
The accumulated travel cost output

Cost accumulates away from source cells

- High values = longer travel time (for example)

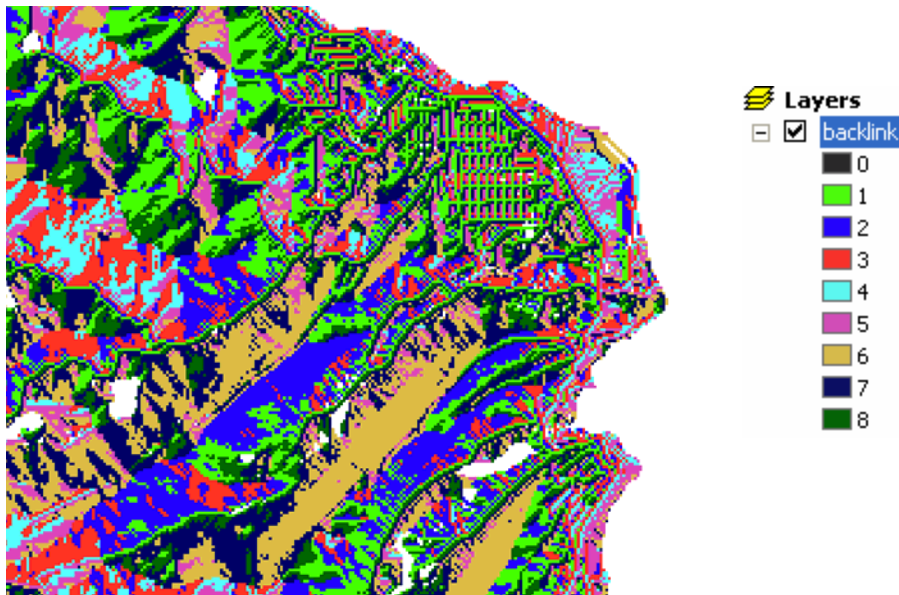
Use as:

- A measure of accessibility
- An input to Cost Path
- An input to Corridor



The backlink output

- ❑ Direction codes point back to the “nearest” source
 - For each cell, points to the adjacent cell on least-cost path
- ❑ Required by the Cost Path tool



The allocation output

- ❑ **Assigns each cell to the nearest* source**
 - A method of assigning space
 - Like Thiessen polygons
- ❑ **Use as a measure of proximity | accessibility**

– Nearest in terms of weighted distance: time, money, etc.

The Path Distance tool

- ❑ Similar to Cost Distance tool but more powerful
- ❑ Considers other factors that affect movement

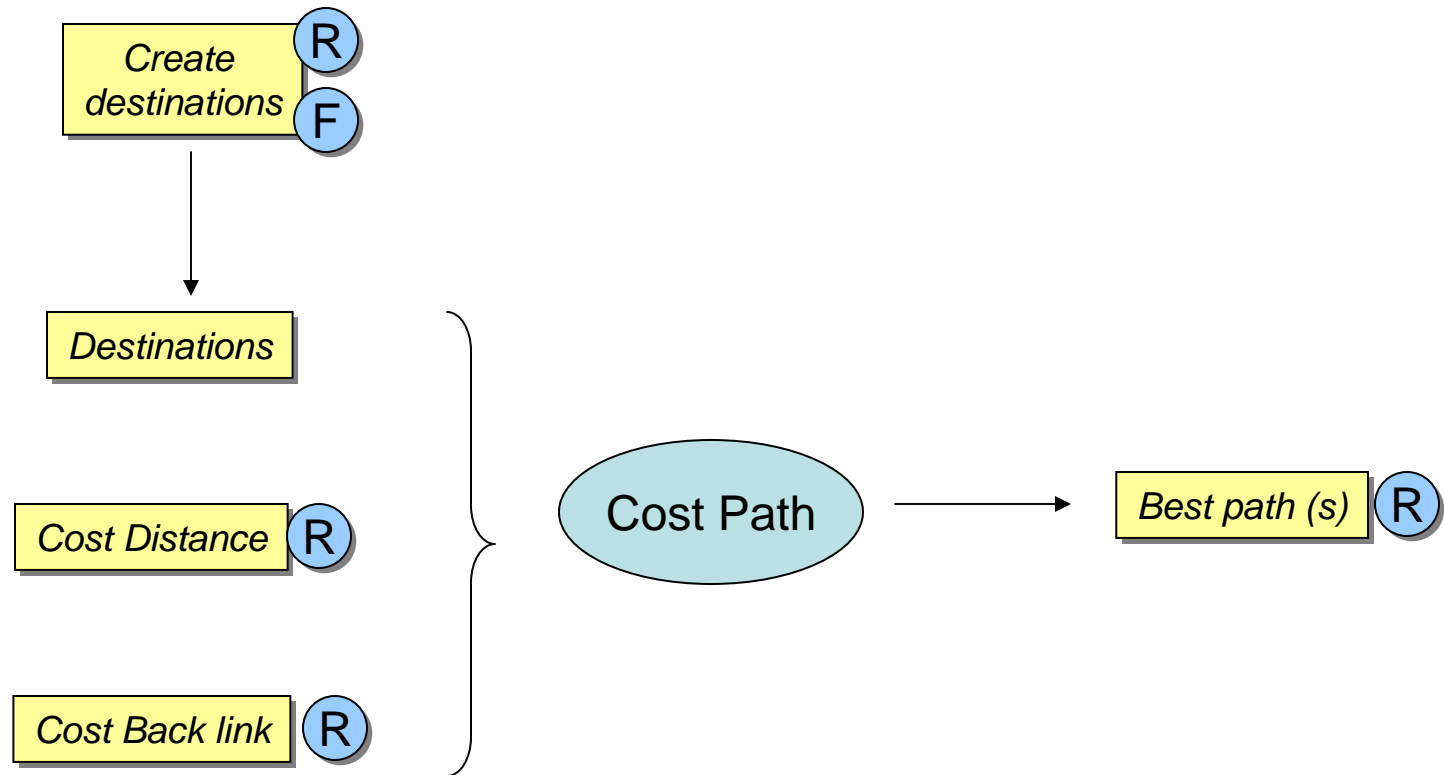
Surface Friction

Vertical Factor

True Surface Length

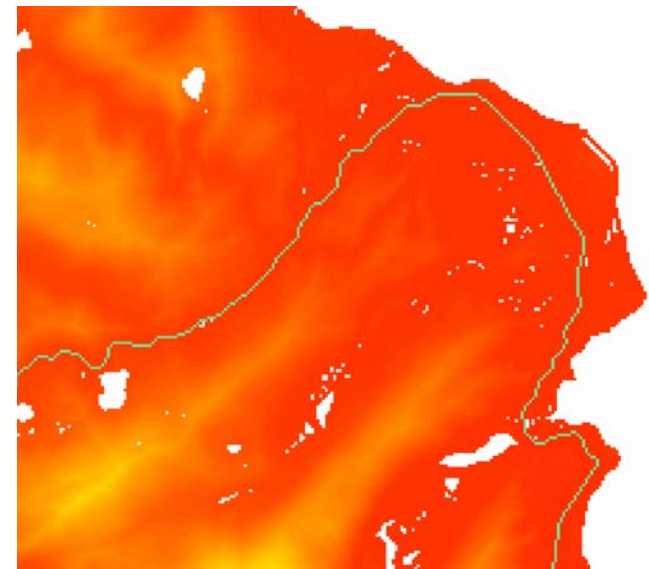
Horizontal Factor

The roadmap - The Cost Path tool

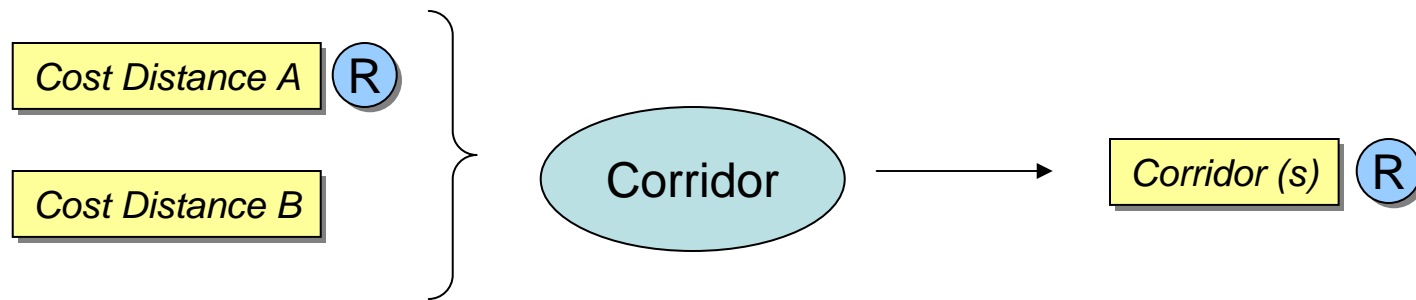


Finding paths

- ❑ **Finds least-cost paths from sources to destinations**
 - **Cost Path = raster lines (with attributes)**
- ❑ **Required inputs**
 - **Destinations**
 - **Cost or Path Distance outputs**
 - **Accumulated travel cost raster**
 - **Backlink raster**



The roadmap - The Corridor tool



Exercise 6 overview

- Find the straight line distance to Rockbound Valley**

- Find the weighted distance to Rockbound Valley**
 - **Create a cost surface**
 - **Speed limit of roads**
 - **Off-road travel costs**
 - **Create the weighted distance and direction rasters**
 - **Find the best path to Rockbound Valley**